# **Considerations on Making Test Stands for Small Hydraulic Turbines**

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*Abstract: Hydraulic turbine test stands represent an important link in the efficient utilization of the energy potential of water flows. The realization of these turbines begins with an approximate design, based on the differential equations of motion of ideal fluids, and continues with successive stages of performance testing in the laboratory, on small-scale models. Using different similarity criteria based on geometric, kinematic and dynamic similarities, the conclusions drawn from the operation of the model will also be valid for the real machine. The purpose of the paper is to present some points of view on the realization of three types of stands for small hydraulic turbines, of which two are patented and one is a patent application. These stands simulate real operating conditions on permanent flowing water with velocities, flows and falls for small hydraulic turbines that can be installed on the water line, in locations that do not use dams or other expensive water storage facilities. The main author of the patent documentation makes a synthesis of the constructive-functional characteristics of the respective stands through this article.*

*Keywords: Test stands, small hydraulic turbines, permanent flowing waters, velocities, flows and water falls*

## **1. Introduction**

The role of a test stand is to reproduce in total geometric similarity the physical phenomena that take place in an industrial turbine. The experimental research of hydropower aggregates is carried out in the laboratories of universities and institutes with concerns in the field, on experimental stands that simulate the real operating conditions of hydraulic turbines. Function of the type of hydraulic energy converted into electrical energy, hydraulic turbines are divided into two categories: "**flow (speed) turbines**", which harness the kinetic energy, respectively the flow rate Q [m<sup>3</sup> /s] or the speed v [m/s] of the water and "**fall turbines",** which exploit the potential energy, respectively the fall H [m] of the water. Therefore, the experimental test stands for hydraulic turbines will be "flow (velocity) stands" [1,2], with larger horizontal dimensions and "drop stands" [3,4], with larger vertical dimensions.

**The load** of the hydraulic turbine mounted on the experimental test stand can be achieved with an electric generator, with the shaft coupled to the turbine rotor shaft, or simulated, with a mechanical / hydraulic braking system, which replaces the electric generator. Three constructive solutions of stands for small hydraulic turbines are presented below; two from the first category [5,6] and one from the second category [7].

## **2. Constructive stand solutions for testing small flow hydraulic turbines**

This chapter presents the constructive solutions for two means of testing small hydraulic turbines, which differ from each other in the water flow (speed) regulation mode and the load simulation system, respectively:

*- a stand for the optimization of the hydrodynamic profile of the blades and functional tests of the rotors of hydraulic turbines*, with which the speed distribution on the rotor blades of axial hydraulic turbines of reduced dimensions and masses can be determined experimentally, successively in two stages, in order to optimize their hydrodynamic profile, in the first stage, as well as the mechanical parameters, speed and moment, of the hydraulic turbine rotors, with the previously experimentally optimized blade profile, in the second stage;

- *a stand with a tilting water ford*, for the experimental testing of scale models, with reduced dimensions and masses, of axial hydraulic turbine rotors, with a vertical or horizontal shaft.

## **2.1. Stand for optimizing the hydrodynamic profile of blades and functional tests of hydraulic turbine rotors**

**Constructive solution** for this stand is shown in figures 1, 2 and 3.



**Fig. 1.** Functional and constructional scheme of the stand



**Fig. 2.** The detail of the turbine with vertical shaft



coupled at adjustable brake system **Fig. 3.**The assembly of the main modules of the stand

The stand in figures 1, 2 and 3 forcibly circulates a volume of clean water in a closed circuit, made by a pumping group with adjustable flow **G.P.D.R**., which sucks from a suction tank of pumps **R.A.P.** and discharges into a modular water tunnel, **T.A.M**., consisting of five horizontal sections, removable and watertight, provided with covers, of which the first three rest on a metal support with adjustable height **S.M.I.R**., and the last one on the suction tank of the pumps **R.A.P.**, with which it communicates. The closed water circuit is made on the route **R.A.P.- G.P.D.R.- T.A.M.- R.A.P.** The first three sections of the modular water tunnel **T.A.M**., from which two have a variable section, contribute to the stabilization and uniformity of the flow in the fourth section, made of a transparent and resistant material, in which the fixed rotor blades are mounted, to determine of the speed

distribution, respectively the axial turbine rotor with horizontal axis **R.T.A.O**., figure 1 or with vertical shaft **R.T.A.V**., figure 2, which is to be tried.

These models of hydraulic turbine rotors couple, through a vertical or horizontal shaft, to an adjustable braking system **S.F.R.,** which simulates the load of the rotor immersed in the modular water tunnel, when it is driven by the kinetic energy of the water.

Through a SCADA monitoring, control and data acquisition system, three transducers and a **PC**  computer, the following is achieved: *the control* of the adjustable braking system and the flow regulation of the pumping group; *the monitoring and acquisition* of the adjustable parameters of the stand, namely the flow rate **Q** and the speed **v** of the water in the fourth section of the tunnel and the mechanical parameters of the adjustable braking system, namely the moment **M** and the rotational speed **n**.

The stand allows the experimental determination of three functional characteristics for the tested hydraulic turbine rotor models, respectively: moment at the rotor axis as a function of flow at constant load, i.e. *M=f(Q) at M<sup>r</sup> =const*., rotor speed as a function of load at constant flow, i.e. *n=f(Mr)* at *Q=const.* and rotor speed as a function of flow at constant load, i.e. *n=f(Q)* at *Mr =const.*

The pumping group with adjustable flow **G.P.D.R.**, located under the modular water tunnel **T.A.M.**, consists of three centrifugal pumps **3**, identical and mounted in parallel to sum up the flows, which have a common suction collector and a discharge collector **1**, each of the three pumps can be separated from the collection pipes of the group by means of two isolation valves **2**, one on the suction and the other on the discharge, with a directional valve **7** installed before the valve on the discharge, and each pump being driven by a motor electric of 380 V ac. **4**, coupled to the pump shaft by means of an elastic mechanical coupling **6** and powered by means of an adjustable frequency converter **5**, with the help of which the drive rotational speed of the pump is regulated and, through it, the flow rate of the pump. The adjustable flow pump group sucks through a suction line **AC** from a suction tank of the pumps **R.A.P.** and discharges through a discharge pipe **C.R.** in a. modular water tunnel **T.A.M**; to prevent the propagation of vibrations generated by the pumping group towards the tunnel and tank, four elastic sleeves **24** are to be installed.

The modular water tunnel **T.A.M**. is composed of five sections provided with covers, removable and watertight, which form a continuous assembly, without thresholds near the joints. In the first section **8**, acting as a diffuser in the flow, the pumped water enters the tunnel through a cylinder made of PVC pipe, with a glued plastic cover, provided with large perforations on its side surface, then meets on its way a plate made of perforated sheet metal, mounted transversely to the flow direction. The second section **9**, of constant section and equal to the exit section of the first section, contains sieve packs, perforated sheet screens and honeycomb structures, all with the role of stilling the flow and equalizing the current lines. The third section **10**, is contraction because its output section is reduced to 1/6 of the input section. The first three sections of the modular water tunnel rest on a metal support with adjustable height **S.M.I.R**. Next comes the test/visualization section **11**, where the water flow is uniform and stable due to the shapes, sizes, quality of the inner surface and the quality of the joints of the first three sections of the tunnel, and the output section **12**, through which the water tunnel communicates and supports with/ on the suction tank of the pumps **R.A.P**.

The suction tank of the pumps, **R.A.P**., contains inside: a deflector, which directs the flow of water from the tunnel to the outlet of the tank; a fine screen, mounted transversely to the direction of water flow in the tank, to break air bubbles and a PVC elbow, at 90°, mounted at the bottom of the tank, to reduce bottom vortexes in the suction area of the pumps.

The axial turbine rotor model with horizontal shaft **R.T.A.O.**, or with vertical shaft **R.T.A.V**., to be tried on the stand, is coupled by means of a horizontal or vertical shaft **20**, to an adjustable braking system **S.F.R.**

Adjustable braking system **S.F.R.** contains: two bearings, one radial **21** and another radial-axial **22**, in the case of coupling to **R.T.A.O**., two bearings radial-axial **22**, in the case of coupling to **R.T.A.V**; a torque and speed transducer **17**; a brake with magnetic powders **18**, with the possibility of horizontal or vertical mounting, with adjustable resistance moment depending on the supply current; a 24 V d.c. electric motor **19**, necessary for driving the brake before carrying out the tests on the stand, for the homogenization of the magnetic powder and the determination of the friction

in the bearings, and three mechanical couplings **23**, from the kinematic chain model shaft rotortorque transducer and speed-brake-24 V d.c electric motor.

The monitoring, control and data acquisition system **SCADA** contains: an electric box, equipped with programmable controller, two electrical sources of supply, for brake and for electric motor of 24 V d.c., four numerical displays, for flow, for differential pressure, for torque and rotational speed; an electromagnetic flowmeter **15** and a flow transducer **16**, mounted on the discharge pipe **C.R**.; a Pitot-Prandtl tube **13**, movable in three orthogonal directions and a differential pressure transducer **14**, mounted on the frame of visualization test section; a **PC** calculator. The **SCADA** system ensures: monitoring and acquisition of four parameters, respectively water flow **Q** and speed **v** (indirect by converting the differential pressure in speed) in the test/visualization section, torque **M** and rotational speed **n** at the shaft of the test rotor model; three controls, one for adjusting the flow of the pumping group, one for adjusting the resisting torque of the magnetic powder brake and one for driving the 24 V d.c. electric motor.

Three frequency converters **5** and three electric fans for cooling the motors are mounted in the electric power cabinet **DE**, which supplies the three electric motors driving the pumps. The electric cabinet ensures: power supply for electric motors of 380 V a.c. starting and stopping the pumping group; monitoring and regulation of the pumping group flow, carried out locally, from the cap of the electric cabinet, by means of three rotatable potentiometers provided with numerical displays.



 **Table 1:** The function of the stand and the tests carried out procedure



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## **2.2. Stand with tilted water ford for testing some hydraulic turbines**

The **constructive solution** for this stand is shown in figures 4...8.



**Fig. 4.** Assembly-mounting drawing and isometric view of the stand

**The hydraulic microturbines test stand** with tilted water ford, figure 4, consists of a water tank **1**,an adjustable flow pumping module **2**, which sucks from the bottom of the tank and discharges at the left end of a water ford with constant section **3,** in the form or trough, mounted on the upper side of the tank, the water ford being equipped, at the opposite end of the water supply ,with a load simulation device 4, and having the possibility of adjustable tilting, with maxim 9°, to the right of the horizontal position, around a shaft **5**, equipped with two bearings and two spacers **10**, when a screw-nut mechanism **8** is manually actuated**,** which moves the lifting cross-bar **7,** mounted on the upper part of the right end of the ford , in front of the lifting cross-bar **6**, mounted at the superior side of the right end of the water tank , each of two cross-bars being equipped with two bearings.

The tilting shaft of the ford **5** and the two lifting cross-bars **6** and **7** are secured at the ends, against the detachment from the bearings, by two screws **11** and two nuts **12** each, and the stand also contains another mechanism screw-nut **9,** which actuates a flat weir, that regulates the water level upstream of it, in the ford **3**.



**Fig. 5.** Assembly-mounting drawing and isometric view of the water tank

The **water tank 1**, figure 5, built of pieces of stainless-steel sheet, welded on a resistance structure of metal profiles **1.1**, is provided at the top, at about half of its height, with a cover made of four tin plates, of which three whole, **1.4** and one perforated, **1.5**. The tank is provided with four bearing supports, **1.2**, of which two, for the ford tilting shaft, are positioned on the left side above the cover, and the other two, for the ford lifting cross-bar, are positioned on the right side. On the left side, close to the bottom of the tank, is positioned the suction flange of the pumping module.



**Fig. 6.** Assembly-mounting drawing and isometric view of the pumping module

The pumping module **2**, figure 6, consists of an electric pump **2.1**, with adjustable flow rate by varying the frequency of the electric drive motor supply current, provided on the suction pipe with an anti-vibration connection **2.2**, a flange connection **2.5**, screws **2.6** and nuts **2.7**, and the discharge pipe **2.4** contains two welded elbows and a water flow diffuser (not figured) in the ford. The pump base is fixed on a pedestal, by means of two vibration dampers **2.3** and four screws **2.6**.



**Fig. 7.** Assembly-mounting drawing and isometric view of water ford

**The water ford 3**, figure 7, contains a tilting frame **3.1**, on which a water through **3.2** is welded, parallelepipedal in shape and made of pieces of stainless-steel sheet, which is closed at the front, on the left side, with a plate **3.4**, and at the opposite end with a **3.7** flat sluice, for regulating the water level in the trough. The ford is also equipped with four bearings **3.3**, two mounted on the lower-left side and two mounted on the upper-right side, a stainless steel sheet perforated screen for stilling the flow **3.5**, transversely mounted, with two skids **3.6**, inside the trough and a flap **3.8** for deflection the flow to the tested turbine, equipped with an angle adjustment lever **3.9**, with penetrated transverse holes, which can be locked in the desired position with the help of a screw **3.10** and a wing nut **3.11**.



**Fig. 8.** Assembly-mounting drawing and isometric view of load simulation device

**The load simulation device 4**, figure 8, consists of a support **4.1**, on which the turbine to be tested is mounted, the turbine shaft being inserted into the bearing **4.2**, equipped at the bottom with a flange for holding the turbine rotor, and at the top with a large diameter gear for a transmission with toothed belt **4.3**, with a 10:1 ratio between the turbine shaft and the gear pump shaft (not figured) that sucks and discharges from/into the water tank , when is driven by the tested turbine, by means of the transmission with the toothed belt, the pump load being carried out by tightening an adjustable needle throttle (hydraulic resistance) **4.7**, mounted on the discharge

pipe of the gear pump, and the pressure created by the load being read on a pressure gauge (not positioned). The load simulating device is fixed with four screws **4.5** and four nuts **4.6** to the upper edge of the water ford **3**, on which a bracket with performed holes for screws is welded. To carry out the tests, the stand is equipped with three transducers (not positioned): one for rotational speed, which measures the rotational speed in the shaft of the tested turbine, one for speed and one for level, which measures the speed / water level in the ford.

The **test flow** is measured indirectly by means of velocity and level transducers. It is expressed with the relation:  $Qp=v \cdot S=v \cdot l \cdot h$ , where  $Qp$  is the test flow rate  $[m^3/s]$ ; *v* is the water velocity in the ford *[m/s]*; *S* is the water flow section in the ford *[m<sup>2</sup> ]*;

The **load** with which the tested turbine is loaded is measured indirectly with the help of the manometer (not figured) on the load simulation device **4**. It is expressed by the relation: *Mr = p·c* where *Mr* is the resisting torque (couple) [*Nm*] with which device loads the tested turbine; *p* is the pressure on the discharge pipe of the gear pump of the device *[10<sup>5</sup> ·N/m<sup>2</sup> ]*, read on the manometer and adjusted from the needle throttle 4.7; c is the gear pump capacity [10<sup>-6</sup>*·cm<sup>3</sup>/rot]* of the device.



 **Table 2:** Stand functionality and the ways of carrying out the tests

*The variation of the flow rate*, regarding the determination of the first characteristic, is carried out in two steps, respectively:

- *establishing a water level upstream of sluice* **3.7** at the minimum flow rate of pumping group **2**  and for the horizontal position of ford **3**;

- *maintaining the predetermined level*, when the ford is positioned horizontally, for its inclined positioning. In this sense, the tilting of the ford with an angle in the range of  $1...9$ <sup>o</sup> will be followed by the increase of the flow rate of the pumping group in the range of *Qmin...Qmax*, by the variation of the electric motor supply frequency in the range of 20...50 Hz.

By adjusting the angle of inclination of the ford, with a step of 1<sup>o</sup>, in the ranges  $0^{\circ}...9^{\circ}$  and  $9^{\circ}...0^{\circ}$ , followed by the adjustment of the centrifugal pump flow, so that the water level in the ford to remain constant (with a tolerance of ±5%),18 distinct turbine test flow values can be obtained.

*The load variation*, regarding the second characteristic, is achieved by actuating the needle throttle **4.7** of the load simulation device **4**. The needle throttle has a fine adjustment characteristic (pressure on the gear pump discharge depending on the throttle opening) which allows that the load simulator device to make a fine-tune of the load of the tested turbine.

## **3. Constructive stands solutions for testing small head hydraulic turbines**

A constructive solution for a stand fed with a constant level reservoir, intended for testing low head hydraulic turbines, is presented in figure 9.



**Fig. 9.** Constructive-functional diagram for a hydraulic turbine test stand fed with constant level tank

**The stand** from figure 9 circulates a flow of clean water in a closed circuit, with the help of a pumping group with adjustable flow, consisting of three centrifugal pumps **3**, identical and connected in parallel to sum up the flows, each of them having a common suction manifold and a common discharge manifold **1**, each of the three pumps being able to be separated from the collection pipes of the group by means of two isolation valves each **2**, one on the suction and the other on the discharge, a one-way valve **7** being mounted before the valve on the discharge, and the drive of each pump being made by an electric motor of 380 V AC, **4**, coupled to the pump shaft by an elastic mechanical coupling **6** and powered by means of an adjustable frequency converter **5**, with the help of which the drive rotational speed of the pump is adjusted and, by through it, the flow of the pump is adjusted.

*The adjustable flow pumping group* sucks through a suction pipe CA from a first suction tank **RI**, mounted on the ground, inside which a wall **PS** is provided to separate the discharge / suction compartments, and discharges through a pipe discharge **CR** into a second upper tank **RS**,

mounted at a height and overlapped on the first one, which has a spillway **PD** separating two compartments, one connected to the discharge pipe and another connected to a transparent vertical pipe connected to the lower tank RI, both tanks having caps that communicate with the atmosphere and being fixed on the same metal support **SM**, equipped with screws for adjusting the verticality of the subassembly tanks-covers-support (not shown in the diagram).

The tributary flow, with which the pumping group feeds the upper tank, drains by gravity into the lower tank through a transparent vertical pipe **8**, provided with a flange glued at one end, which is mounted between the tanks, the flanged end of the pipe being fixed to the bottom of the upper tank, inside, and the other end, which penetrates the cap of the lower tank, remaining permanently completely immersed in water. To prevent the propagation of vibrations, generated by the pumping group, to the two overlapping tanks are equipped with two elastic sleeves **24**.

Each of the two tanks also contains: an emptying valve, **13** and **16**, mounted in a T-shape connection, in which the hydrostatic pressure transducers **12** and **15** are also mounted; one level indicator each, **11** and **14**. In case of accidental damage to the automatic flow regulation system, an overflow pipe **CPP** is considered, through which any excess flow will be discharged from the upper tank to the lower tank*.*

**The model 23** low-head hydraulic turbine to be tested on the stand is mounted inside the upper tank, with the turbine stator fixed to the flange of the transparent tube and the rotor coupled to the shaft **20** of an adjustable braking system resting on the upper tank cap.

*The adjustable braking system* contains: two radial-axial bearings **21**; a torque and rotational speed transducer **17**; a brake 18 with magnetic powders, with adjustable resistance moment depending on the supply current; an electric motor 19 of 24 V d.c., necessary to drive the brake before the start of tests on the stand, to homogenize the magnetic powder and determine the value of the friction moment in the bearings, and four mechanical couplings 22 on the kinematic chain of the components of the braking system.

**The SCADA system** for monitoring, control and data acquisition contains: an electrical box, equipped with a programmable controller and power source; two transducers, **12** and **15**, mounted at the base of the tanks, which measure the hydrostatic pressures, **p<sup>1</sup>** and **p2**, in each tank, and are used to measure the water levels **h<sup>1</sup>** and **h<sup>2</sup>** in each tank; an electromagnetic flow meter **9** associated with a flow transducer **10**, mounted on the discharge pipe of the pumping group; a brake **18** with magnetic powders; a torque and a rotational speed transducer **17** in connection with a **PC** computer, by means of which the adjustable braking system is controlled, i.e. the regulation of the flow to the pumping group, so that the drop **H** achieved by the transfer of a volume **V** of water from the lower tank to the upper tank and defined so that the distance between the free surfaces of the water in the two tanks remains constant, at a prescribed value, during the tests. Through the **SCADA**, the test flow rate **Q**, the levels **h<sup>1</sup>** and **h<sup>2</sup>** of the water in the two tanks and the mechanical parameters of the tested turbine (rotational speed **n** and moment **M**) are monitored.

*By changing the prescribed H<sup>p</sup> drop*, respectively the stabilized **NF1**, **NF2** levels of tank operation, measured with transducers **12** and **15**, the **SCADA** system of the stand can adjust the achieved drop **Hr**, in an interval of length proportional to the volume of the tanks and the **Z**  elevation of the front positioning of soil of the **RS** tank. Each adjusted value of the drop H will correspond to a value of the influent flow rate to the upper tank, equal to the effluent flow rate of the tank that flows through the transparent tube, respectively the flow rate required to test the model 23 of the tested low-head hydraulic turbine.

*The determination of the functional characteristics* of the low-head hydraulic turbine models tested on the stand is done after the homogenization of the magnetic powder from the brake, by operating it in empty position, for 10-15 min., with the help of the electric motor of 24 V d.c.**19,** followed by its dismantling.



 **Table 3:** Stand functionality and the ways of carrying out the tests





### **4. Conclusions**

The summary of the main conclusions is presented in table 4.

 **Table 4:** Synthesis of the main conclusions



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